# GENERAL DYNAMICS

Mission Systems

# **VRIP**

# Low Latency, High Definition Video Router and Image Processor



### Video Routing/Encoding/Decoding

Image Enhancement	
Operator Aids	
Image Controls	
Sensor Fusion	

### **Overview**

The Video Router and Image Processor (VRIP) unit provides low-latency, low-cost video routing and processing and streaming capabilities suitable for the most demanding in-vehicle high definition video distribution applications such as Situational Awareness Systems.

The VRIP unit is an open standard 3U VPX chassis containing a GDMS-C VP1-1 Video Processor, a Graphics Processing Module, and power supply.

The VRIP supports the following I/Os:

#### Video inputs:

- 4x SD def CVBS/RS-170A (NTSC/PAL)
- 4x 3G SDI up to 1920x1080 resolution
- 1x HD SDI up to 1920x1080 resolution
- 2x DVI up to 1920x1080 resolution
- 1x RGsB or VESA VGA analog component up to 1280x1024 resolution
- 1 x H.264 SD Decoded video streams
- 1x H.264 HD Decoded video streams

## Video outputs:

- 4 x 3G SDI Outputs up to 1080p60 resolution
- 1 x DVI up to 1920x1080 resolution
- 4 x SD H.264 Encoded video
- 1 x SXGA H.264 Encoded video

The control API is accessed via a dedicated Ethernet port.

# **Technical Information**

### **Features:**

- Image Enhancement:
  - Mirroring: used for Rear facing cameras;
  - Histogram: used for low contrast scene enhancement in fog, smoke, overcast snow or sand, etc.;
  - Image Sharpening: used to enhance brightness and edges;
  - Local Equalization: used for local contrast enhancement;
  - Horizon Compensation: used to automatic adjustment contrast in bright sky or low sun angle situations.
- Operator Aids:
  - Change Detection: automatic detection of transient flashes such as gun firing and windscreen glint;
  - Automatic Target Detection: provides a video overlay of possible targets based on contrast, size & co-location;
  - Target Tracking: Tracking of designated object.
- Image Controls:
  - Stitching: used to combine video streams with adjacent horizontal boundaries and output a single stitched image; and
  - Stabilization: scene based stabilization to remove vibration artefacts.
- Sensor Fusion: used to combine two video streams by combining corresponding pixels from two video cameras into a single output pixel representative of information from both sources.
- Video Routing: Any to any routing available with customizable firmware. Base routing available today.
- Video Encoding/decoding: STANAG 4609.
- Multi-view outputs: Picture in Picture (PIP) and multi view displays.
- Customizable graphics overlay on all video outputs.
- Real Time Video Processing: scaling, layering, positioning, and routing as well as the blending of any input or output video.
- Dual-core A9 Cortex Processor: used to host applications.

### **Interfaces**

User Application CPU: Dual-Core ARM Cortex-A9 (1.05 GHz)

Network: 3x 10/100/1000 Ethernet

 USB:
 2x USB 2.0

 Serial:
 1x RS422/RS232

 Audio:
 1x Mono Input

 1x Mono Outputs

Video Input Interfaces: 4x CVBS/RS-170A (NTSC/PAL)

4x 3G SDI up to 1920x1080 resolution
1x HD SDI up to 1920x1080 resolution
2x DVI up to 1920x1080 resolution
1x RGsB or up to 1280x1024 resolution

Video Output Interfaces: 4 x 3G SDI Outputs up to 1920x1080

resolution

1x DVI up to 1920x1080 resolution

Video Latency: As low as 1 frame
Power Input: MIL STD 1275D

Video-Over-Ethernet: STANAG 4609. H.264 SD and HD Video

Decode

STANAG 4609. H.264 SD and SXGA Video

Encoding

\*Optional low bandwidth (1Mbps) secondary

stream per encode
1x Mono encoding

(AAC @ 128/192/256/320Kbps) Support for KLV metadata

On-Screen-Display: Multiple independent OSDs supported

(OSD Overlays)

Operating Systems: Linux **Physical Characteristics** 

Size: 11.35" d x 6.79" w x 5.75" h

Weight: 15 lbs Connectors: MIL-C-38999

### **Environmental Specifications**

Operating Temperature: -40C to +49C Storage Temperature: -51C to +71C

Vibration: MIL-STD-810G Method 514.5 Procedure I

Composite Tracked and Wheeled Vehicle

Shock: MIL-STD-810G

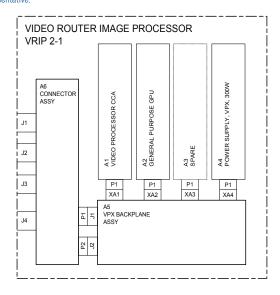
Operational: Method 516.5, Procedure I
Bench Handling: Method 516.5, Procedure VI
Crash Hazard: Method 516.5, Procedure V

EMI/EMC: MIL-STD-461F

### **Additional Features**

- Built-In Test (BIT)
- Two level maintenance support

The processor described here represents a general configuration of this family of products. Specifications are configurable for specific customer requirements. For pricing and availability interfaces, casings, connectors and other information, please contact your General Dynamics representative.



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